

aThis Page Is Inserted by IFW Operations
and is not a part of the Official Record

BEST AVAILABLE IMAGES

Defective images within this document are accurate representations of the original documents submitted by the applicant.

Defects in the images may include (but are not limited to):

- BLACK BORDERS
- TEXT CUT OFF AT TOP, BOTTOM OR SIDES
- FADED TEXT
- ILLEGIBLE TEXT
- SKEWED/SLANTED IMAGES
- COLORED PHOTOS
- BLACK OR VERY BLACK AND WHITE DARK PHOTOS
- GRAY SCALE DOCUMENTS

IMAGES ARE BEST AVAILABLE COPY.

**As rescanning documents *will not* correct images,
please do not report the images to the
Image Problem Mailbox.**

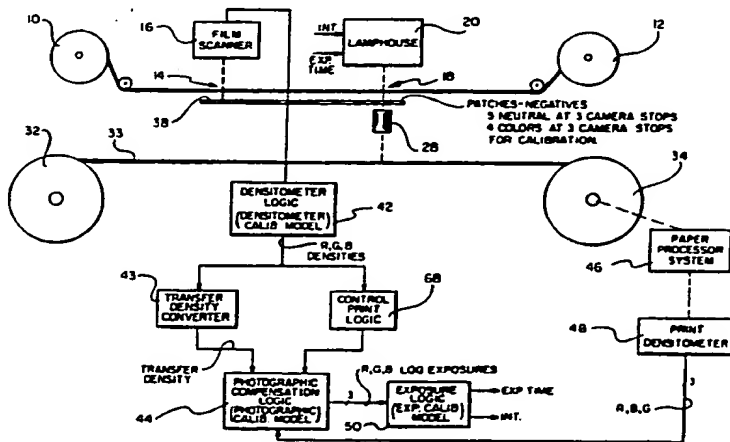
This Page Blank (uspto)

INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification ⁴ :	A1	(11) International Publication Number: WO 89/ 03062
G03B 27/73		(43) International Publication Date: 6 April 1989 (06.04.89)
<p>(21) International Application Number: PCT/US87/02531</p> <p>(22) International Filing Date: 1 October 1987 (01.10.87)</p> <p>(71) Applicant: EASTMAN KODAK COMPANY [US/US]; 343 State Street, Rochester, NY 14650 (US).</p> <p>(72) Inventors: GOODWIN, Robert, Melvyn ; 29 Tree Brook Drive, Rochester, NY 14625 (US). COS- GROVE, Patrick, Andre ; 82 Troutbeck Lane, Ro- chester, NY 14626 (US).</p> <p>(74) Agent: BRANDT, Jeffrey, L.; 343 State Street, Roches- ter, NY 14650 (US).</p> <p>(81) Designated States: CH (European patent), DE (Euro- pean patent), FR (European patent), GB (European patent), JP.</p>		<p>Published <i>With international search report.</i></p>

(54) Title: SYSTEM FOR CALIBRATION AND CONTROL OF A PHOTOGRAPHIC COLOR PRINTER

(57) Abstract



FOR THE PURPOSES OF INFORMATION ONLY

Codes used to identify States party to the PCT on the front pages of pamphlets publishing international applications under the PCT.

AT	Austria	FR	France	ML	Mali
AU	Australia	GA	Gabon	MR	Mauritania
BB	Barbados	GB	United Kingdom	MW	Malawi
BE	Belgium	HU	Hungary	NL	Netherlands
BG	Bulgaria	IT	Italy	NO	Norway
BJ	Benin	JP	Japan	RO	Romania
BR	Brazil	KP	Democratic People's Republic of Korea	SD	Sudan
CF	Central African Republic	KR	Republic of Korea	SE	Sweden
CG	Congo	LI	Liechtenstein	SN	Senegal
CH	Switzerland	LK	Sri Lanka	SU	Soviet Union
CM	Cameroon	LU	Luxembourg	TD	Chad
DE	Germany, Federal Republic of	MC	Monaco	TG	Togo
DK	Denmark	MG	Madagascar	US	United States of America
FI	Finland				

-1-

SYSTEM FOR CALIBRATION AND CONTROL
OF A PHOTOGRAPHIC COLOR PRINTER

Technical Field

The present invention relates to a system for calibrating and controlling a photographic color printer, and particularly to a computer controlled system which is calibrated on a statistical basis for the spectral response characteristics of the densitometer, exposure control device, photographic print media and processing system which are used to make prints of color negatives.

The invention is especially suitable for use in a high-speed color printer and maintains calibration notwithstanding that tens of thousands of prints per hour can be produced and different types of paper can be used which can be changed from time to time. The invention is generally applicable to photographic printing systems and may be used to provide prints of high quality, reliably over long periods of time.

Background Art

Calibration or set up of color printers which are in use today by photofinishers has been accomplished by a manual adjustment process based upon subjective analysis of prints made with test negatives by skilled personnel. In U.S. patent 4,526,462 issued July 2, 1985 a computer controlled calibration system is proposed which uses prints made from reference negatives which are both overexposed and underexposed and a standard print to obtain a model for color correction which will obtain color balance referenced to the standard print. The use of under and overexposed reference negatives allows the nonlinear density versus exposure time

- 2 -

characteristic of the photographic printing paper to be tracked thereby to achieve correction factors of exposure times over a reasonable range of negative densities. In U.S. patent 4,646,045 issued August 7, 1984 a special calibrating negative is used having several steps of different density. Prints made from this wedge are utilized to provide correction factors to provide color balance over a range of densities of a production negative. Inasmuch as the interactions of the densitometer which scans the negatives, the exposure device, the paper and the printing process are not defined and vary from printer to printer, the use of standardized or reference prints to derive correction factors is an empirical process, even using the results of exposures and prints of reference negatives.

Disclosure of Invention

It has been found, in accordance with the invention, that a model of the complex scanner, printer, paper and print processing systems must be statistically based in order to make the control of the exposure (both the intensity of the color components of the illumination and the exposure times) independent of variations in scanners and the effects of different exposure control hardware, photographic paper properties and the development process, as well as their interactions. Through the use of the calibration models obtained in accordance with the invention a transfer density may be used which is dependent upon the negative to be exposed and is independent of the variations in the scanner and the exposure control device, photographic paper and printing process and their interactions. Thus, each negative will produce a standardized result in all printers so calibrated.

- 3 -

The system generates a calibration model for the densitometer of the printer and another calibration model for the photographic system of the printer including the exposure control device, the paper and the processing system. These models are derived by regressions using statistical data obtained from a set of calibration patches. Each patch covers a different level of a different color and neutral. For example in a preferred embodiment a set of seventeen calibration patches is used consisting of three levels (each of a different f-stop, e.g. - 2 , + 2 and + 6) of four color variations and five neutral variations. The color variations, in the preferred embodiment may be green, magenta, sky and tungsten ring (incandescent lamp). The set, thus, represents the entire range of negative densities that are encountered in an average film population. These calibration patches are used to provide all the necessary statistical information by exposing them with different exposures (e.g., a full gamut of offsets) to derive prints from which statistical data can be collected by a densitometer. This statistical data is used in regression based computations to produce the models describing the overall system response. These models are used to translate the transfer densities into signals of value which set the exposure control device (both intensity of color components of the illumination and exposure time) to obtain prints of high quality.

Accordingly, it is the principal object of the present invention to provide an improved system for calibrating and controlling a photographic color printer.

- 4 -

It is a further object of the invention to provide an improved calibration system for a color printer in which the system is modeled on a statistical basis in order to derive correction factors by which transfer densities can be translated into signals for operating an exposure control device to expose the negative, whereby to produce a quality print of standardized print density in each color component thereof.

It is a still further object of the present invention to provide an improved system for calibrating a color printer and to make exposures of negatives independent of the response characteristics of the scanner, exposure control device, photographic paper and photographic processing system which can operate automatically whenever calibration is needed.

Briefly described, the invention may be embodied in a photographic printing system for exposing a printing medium through film negatives with light having color components of different intensity and different exposure times. The printing system has a film densitometer for detecting the density of the negatives and an exposure device for providing light having the color components with different intensities and with different exposure times. The system provided by the invention calibrates the printing system to expose the printing medium through the negatives to provide upon processing of the medium in a processing system prints of desired density irrespective of the variations in density readings and spectral response of the densitometer, the printing medium, the processing system and the exposure device. The calibrating system

- 5 -

makes use of a set containing a plurality of negative film patches including a first plurality of patches which vary in neutral density and second pluralities of patches of different color. Each of the second plurality of patches includes a plurality of patches of different density such that the set includes substantially the entire range of negative densities encountered in an average population of color negatives. Means are provided utilizing the patches for deriving a calibration model of the densitometer which emulates the response of the printing medium. Means are also provided utilizing the patches and a plurality of prints made with a different combination of color component intensities of each of the patches for deriving a photographic calibration model which relates the density of the negatives to the density of the prints made by exposing and processing the printing medium. Finally the system includes exposure control means utilizing the densitometer calibration model and the photographic calibration model for controlling the color component intensities and exposure times in the exposure device. Thus, when production negatives are scanned by the densitometer and the calibration models are applied, transfer densities are accurately mapped to the required density on the processed prints independent of the characteristics of the densitometer, exposure device, printing medium and processing system. The transfer densities are translated by the exposure control means into signals for controlling the exposure control device to obtain standard exposure results; for example of densities RGB = 0.8, 0.8, 0.8.

- 6 -

Brief Description of Drawings

The foregoing and other objects features and advantages of the invention as well as a presently preferred embodiment thereof will become more apparent from a reading of the following description in connection with the accompanying drawings in which:

FIG. 1 is a functional block diagram which schematically illustrates a photographic color printer embodying the calibration and control system of the present invention;

FIG. 2 is a schematic diagram illustrating the spatial relationship of the film scanner (densitometer) exposure device and calibration patch as assembled in the system shown in FIG. 1;

FIG. 3 is a block diagram illustrating the interrelationship between the hardware components which provide the system illustrated in the functional block diagram of FIG. 1;

FIG. 4 is a diagram illustrating the structure of the software (computer programs) which are effective in obtaining the functions illustrated in the functional block diagram of FIG. 1;

FIG. 5 is a flow-chart illustrating the program for obtaining the film densitometer calibration model shown in FIG. 4;

FIG. 6 is a flow-chart illustrating the program for obtaining the photographic calibration model shown in FIG. 4;

FIG. 7 is a flow-chart illustrating the program for the photographic calibration regression shown in FIG. 6; and

FIG. 8 is a flow-chart illustrating the use of the exposing device calibration model shown in FIG. 4.

- 7 -

Detailed Description

Referring to FIGS. 1 and 2 there is shown, schematically a color printer which provides prints from negatives which are advanced between a supply reel 10 and a takeup reel 12 to a first station 14 where the negative is scanned by a film scanner 16 and thence to a second station 18 where the negative is exposed by an exposing or exposure device, illustrated as a lamphouse 20. The film scanner is a densitometer utilizing a video camera or a matrix array of photocells. A camera having a charge coupled device (CCD) sensor array may also be used. The camera or photocells, suitably of twenty-four rows and thirty-six columns, resolve the scanned negative into a matrix of pixels. The twenty-four by thirty-six matrix contains eight hundred and sixty-four pixels, the film scanner provides a full matrix for each color (RGB) for a total of 2,592 measurements per scanned image.

The lamphouse, as shown schematically in FIG. 2 contains three color attenuation discs 22 which vary the intensity of the color components (RGB) in accordance with their angular positions. The illumination source is one lamp 24 or three lamps, one for each color. The light passing through the discs enters a mixing chamber which is part of the lamphouse and then passes through a shutter/lens assembly 26 at the output of the lamphouse.

The light after passing through the negative at the exposure station 18 is focused by a zoom lens 28 on the printing medium (paper) at a stage 30 containing suitable masks and guides. The paper is reeled between a paper supply reel 32 and a paper takeup reel 34, as shown in FIG. 1.

- 8 -

A plurality, in this embodiment seventeen (17), film negative calibration patches 36 are mounted along a path paralleling the periphery of a carrier disc, indicated as a carousel 38. This carousel is dimensioned such that the patches can be moved to the negative scanning station 14 and to the negative exposure station 18 by rotating the carousel with a stepper motor 40. During production runs, openings in the carousel are in the light path at each station 14 & 18.

In the exposure device 20, the intensity of the color components is varied by intensity control signals which operate motors for rotating the attenuation discs 22. Three such signals may be used. The exposure time is varied by controlling the shutter 26 using an exposure time control signal.

In order to make the film scanning densitometer 16 emulate the response of the photographic paper, densitometer logic 42 is implemented by software to provide a densitometer calibration model. The output of this model is RGB density data as to the densities of the production negatives which are moved between the reels 10 and 12 or of the calibration patches during the calibration or set up of the printer. It will also be appreciated that the system includes motor drives and controls for the negatives and the photographic paper which may be computer controlled. The printer operates under computer control for calibration as well as in the production of prints.

The densitometer data is applied via a transfer density convertor 43 and control print logic 68 to photographic compensation logic 44, also implemented by

-9-

software, to form a photographic calibration model which processes the RGB density data as well as statistical data made from the calibration patches. This is accomplished through the use of the exposure device 20 and the photographic paper.

The calibration patches 36 in this embodiment consist of five neutral (N) patches each of different density, made as by being exposed at different camera (f) stops between - 2 and + 6. Suitably these camera stops are - 2, 0, + 2, + 4 and + 6. There are twelve sets of monochromatic patches each of a different color which in this embodiment are green (G), magenta (M), sky (S) and tungsten ring (incandescent lamp illumination) (T) (viz. two sets of orthogonal colors) each at a different print density from - 2 to + 6 f stops. Suitably, these density levels are obtained by exposures of the monochromatic patches at + 2, - 2 and + 6 f stops.

In order to obtain statistically sufficient data, each of these patches is exposed three times with a designed set of exposure offsets. Each set is a different combination of RGB offsets derived using an incomplete three level full factorial design. These may be 0.15 density (on the conventional log density scale). A suitable set of offsets is shown in Table 1 where the exposure offsets indicated by a minus 1 are -.15 density, by a plus 1, +.15 density and by a 0 (no delta). The size of the offsets are determined by ensuring that the resulting paper density differences are large compared to the error in the paper densitometry, but not so large as to fall in the toe or shoulder of the paper's density vs. log exposure curve.

SUBSTITUTE SHEET

- 10 -

TABLE 1

	<u>Patch ID</u>	<u>R</u>	<u>G</u>	<u>B</u>
1)	-2G	0	-1	-1
2)	-2M	0	0	0
3)	-2N	-1	-1	+1
4)	-2S	+1	0	+1
5)	-2T	-1	-1	0
6)	0N	+1	-1	0
7)	+2G	0	-1	+1
8)	+2M	+1	-1	-1
9)	+2N	-1	+1	+1
10)	+2S	+1	+1	0
11)	+2T	0	+1	0
12)	+4N	-1	-1	-1
13)	+6G	0	-1	0
14)	+6M	0	+1	+1
15)	+6N	-1	+1	0
16)	+6S	0	+1	-1
17)	+6T	+1	+1	-1
18)	-2G	+1	0	0
19)	-2M	+1	+1	+1
20)	-2N	0	0	-1
21)	-2S	-1	+1	-1
22)	-2T	+1	0	-1
23)	0N	-1	0	+1
24)	+2G	-1	0	0
25)	+2M	0	0	+1
26)	+2N	0	-1	-1
27)	+2S	-1	-1	+1
28)	+2T	+1	-1	+1

- 11 -

29)	+4N	0	0	0
30)	+6G	+1	0	+1
31)	+6M	-1	-1	0
32)	+6N	+1	-1	-1
33)	+6S	+1	-1	0
34)	+6T	0	-1	+1
35)	-2G	-1	+1	+1
36)	-2M	-1	-1	-1
37)	-2N	+1	+1	0
38)	-2S	0	-1	0
39)	-2T	0	+1	+1
40)	0N	0	+1	-1
41)	+2G	+1	+1	-1
42)	+2M	-1	+1	0
43)	+2N	+1	0	0
44)	+2S	0	0	-1
45)	+2T	-1	0	-1
46)	+4N	+1	+1	+1
47)	+6G	-1	+1	-1
48)	+6M	+1	0	-1
49)	+6N	0	0	+1
50)	+6S	-1	0	+1
51)	+6T	-1	0	0

It will be seen from the above table that there are printed three sets of prints for each of the seventeen calibration patches, or a gamut of 51 calibration prints.

After printing, the paper is removed from the takeup reel 34 and processed by the paper processing system 46 (which includes the photographic development chemistry) into the 51 prints. These prints form the basis of obtaining a universe of data from which the

- 12 -

photographic calibration model can be derived by mathematical statistical computations. The prints are scanned by a print densitometer 48 to provide RGB densities from each print. The densitometer may be of commercial design and tied into the computer system, which provides the logic 42 and 44, by a data communication link (modem or interface).

The photographic calibration model stores a matrix of coefficients and offsets which use the RGB densities from the densitometer logic 42 to provide RGB log exposures which compensate for the variations both in the scanner 16 and in the photographic system including the processing system (including variations in paper emulsion batches). Therefore, any production negative will be exposed to produce a standard result.

To obtain the intensity signals and exposure time signals from these log exposures, exposure logic 50 processes the log exposure data from the photographic compensation logic 44. The exposure logic contains an exposure calibration model to derive the exposure time and intensity signals which are then used to control the exposure device (lamphouse 20). During production each negative is scanned by the film scanner 16. The matrix of pixel signals is processed by the densitometer calibration model, then by the transfer density convertor 43, and then by the photographic calibration model to provide the RGB log exposure. The exposing device is then set so that when the negative reaches the printing station 18 it will be exposed with the desired exposure both in color intensities and time.

Referring to FIG. 3 there is shown the hardware components of the printer, several of which have been

- 13 -

discussed above in connection with FIGS. 1 and 2. The film handling hardware includes the reels 10 and 12 as well as the total mechanisms for moving the film. The paper handling hardware includes the reels 32 and 34 as well as the various mechanisms for handling the photographic paper 33 which is transported between the reels and stops at the printing station 18.

The densitometer logic 42, the photographic compensation logic 44 and the exposure logic 50 are implemented by software in a central processing unit 52. This unit may use disk storage 54 for all of the statistical data obtained from the print densitometer and from the scanner 16 as well as temporary storage for the intermediate calculations which are used in deriving the models. The model coefficients and offsets are also maintained in disk storage 54. A single processor (e.g. a super micro, such as a Motorola 68,000 series microprocessor based computer) or a plurality of computers operating as parallel processor may be used to provide the CPU 52.

FIG. 4 illustrates the structure of the software (computer programs) which is used in the system both in calibration and in making production prints. This includes software (computer program) whereby the film densitometer model 60 is produced. It produces RGB printing densities. These values are then sent through a transfer density convertor 43 which implements an exposure determination algorithm 64 (implemented in the software) which produces transfer densities. This algorithm can be of the type used in the art where neutral and color exposures are automatically calculated as a function of scene content, or it can be as simple

- 14 -

as allowing an operator to manually modify the exposure given to a negative based upon the operator's visual evaluation of the scene content. The resulting "transfer density" is a generic exposure that is free of any specific printer characteristics. This transfer density is then fed into the photographic calibration model 62 of the printing system, and translated to an absolute log exposure which does include specific set up and control information. Finally, this absolute log exposure is put through the exposing device calibration model 66 which translates the absolute log exposure to a physical combination of color light intensities and exposure times to produce a good print.

Transfer densities are the equipment independent output of the exposure determination algorithm. When sent to the photographic compensation logic 44 and exposure logic 50, they produce prints of similar quality, regardless of variations in the scanner, exposure device, or in the photographic paper or process.

A photographic calibration model 62 which implements the photographic compensation logic is also implemented by software. The exposure calibration model 66 which implements the exposure logic 50 is also part of the software structure. The control print logic operates on the printing density output of the printing densitometer and provides digital data (the statistical data) which is used in deriving the photographic calibration model. In the case of the normal neutral print the control print logic checks balance or in the case of the gamut prints, it adds the exposure deltas (Table 1).

- 15 -

Consider first the film densitometer calibration model program, the flow-chart of which is illustrated in FIG. 5. Referring to FIG. 5, the output of the scanner is assumed to be outputs from each of the matrix of photocells which defines a pixel of the scanned negative. This is a 24 x 36 matrix which provides 864 outputs per scan. There are three outputs from each photocell (for each pixel) so as to obtain the RGB densities of the film being measured. It will be noted that the scanning densitometer 70 has its own light source and a light conduit (with lenses) to conduct light through the calibration patches 36 and the production negatives. First, using only the scanner and two special filters which are inserted between the light source and the scanner in the location for the calibration patches (on the carousel). These special filters may be provided by some of the neutral patches. The voltages from each photocell are measured. A low density calibration filter and a high density calibration filter are used. Suitable densities for these filters are 0.7 and 2.7. These filters may be Inconel filters because of their spectral neutrality and stability. The measurement determination is indicated at 78.

The measurements are converted into digital values by analog to digital conversion. The outputs are A/D counts. The conversions determination is shown at 80 in FIG. 5. The voltages are measured through variable gain amplifiers, which also have adjustments for offset or bias voltages. Adjustments are made (block 82) to adjust the value of the digital data. The same high and low count is obtained for a given color using the low and high density calibration filters.

- 16 -

Calibration for color is carried out by measuring off line the spectral transmittance of the calibration patches 36 with a spectrophotometer. The resultant transmittance vs. wavelength curve (spectral response) is multiplied by the red, green and blue spectral sensitivity curves of the photographic paper for each calibration patch to obtain data defining three new curves for each patch. The exposing device (the light source 70) average spectral intensity is then used to multiply the data for each of the curves to obtain data for new curves. The area under the new resulting curves is integrated in order to obtain red, green and blue "aim printing densities" for each calibration patch. These aim printing densities are theoretically what the densitometer 16 should measure if the spectral sensitivity of each of the three (RGB) channels of the densitometer 16 exactly matches the spectral sensitivities of the photographic paper. This process is represented by block 84, since it determines the calibration patch aim printing densities.

The average of the digital counts for each color of each calibration patch is then determined in the measurement and A/D process 86. The process also includes averaging the digital counts for each color of each calibration patch. From the aim density data and the average A/D counts for the calibration patches 36, a regression calculation is carried out in the CPU 52 (FIG. 3) to obtain the film densitometer calibration model. This process is indicated at 88 in FIG. 5. The regression computation uses the average digital counts for each color of each patch as the independent

- 17 -

variables and the aim densities of each color of each calibration patch as the dependent variables. The regression analysis may include a 17 x 3 matrix. The result using such a matrix is a 3 x 3 matrix of coefficients and a 1 x 3 matrix of offsets. The regression equation is set forth below. The location of the matrix of coefficients and the matrix of offsets is also indicated.

$$A * M + O + \epsilon = P$$

where:

A is a 17 x 3 matrix of Average A/D counts.

M is the 3 x 3 regression coefficient matrix.

O is the 1 x 3 matrix of regression offsets.

ϵ is a 17 x 3 matrix of errors between the calculated values of P and the measured values of P. The sum of the squares of all ϵ values is minimized.

P is the 17 x 3 matrix of aim printing densities.

The film densitometer calibration model so obtained is utilized by measuring the photocell voltages of all pixels of all three colors for the film negative

- 18 -

being measured. These voltages are then converted to digital counts and transferred to the CPU for calculations. The RGB digital counts for each pixel are multiplied by the 3×3 matrix of coefficients, and the 1×3 matrix of offsets are added to obtain "printing densities" as shown in FIG. 4. These are the densities that would be measured if the photographic paper were used as the densitometer.

The structure of the program for determining the photographic calibration model is illustrated in FIG. 6. A computational model is obtained for the interactions of the film densitometer and the exposing device 20. The model is fixed and need not be changed as long as the film densitometer model or the exposing device model is changed when a change is made in their respective hardware. A recomputation of the photographic calibration model is called for when the photographic printing paper to be used is of a different type than for the model for which it was originally computed. As a practical matter, if the film densitometer or the exposing device is changed and its respective model is changed to compensate for the physical change, the photographic calibration model may need to be recomputed if there was a large change. A large change can be determined by the results obtained from the system; for example if the print quality changes.

In computing the photographic calibration model, the printing densities of the calibration patches is obtained by using the densitometer 16. This process is indicated at 90 and involves measuring the voltages

-19-

from all the photocells in the film densitometer, converting to digital counts and applying the film densitometer calibration model. The average of all pixels for each color of each patch is used to obtain the RGB printing densities for each patch. With 17 patches this results in 17 x 3 or 51 averages. The next process is verification of nominal balance 92. This is done to insure that the calibration prints will have densities within a reasonable range, preferably, but not necessarily on the straight line portion of the density vs. log exposure curve for the paper. The normal neutral patch is used for this test. This is the calibration patch that has a printing density closest to the average of a large population of negatives containing normal scenes. The same calibration patches used to determine the film densitometer model may be used, but the aim densities calculated for these patches are not used. It may be desirable to use several carousels with different patches. Special patches for the determination of the densitometer calibration model, may involve the use of the expensive Inconel neutral density filters. Since the carousels containing the photographic model calibration patches are used more frequently they may be interchanged with the carousel containing the patches which are used in obtaining the densitometer calibration model.

In verifying the nominal balance, (90 - FIG. 6) the RGB log exposures are obtained using a nominal photographic calibration model (a certain array of coefficients and offsets). The model developed in a previous calibration may be used, if it is contained in

SUBSTITUTE SHEET

- 20 -

disk storage 54 (FIG. 3). A suitable matrix of coefficients and offsets is given below.

[1.0	0.0	0.0]
[0.0	1.0	0.0]
[0.0	0.0	1.0]

Initial offsets are determined by trial and error, if no previous results exist. The values of these offsets will depend on many different parts of the system. If no previous information exists, an identity matrix may be used. This matrix makes no assumptions as to the RGB interactions.

A print is exposed through the normal neutral patch with the exposing device using the RGB log exposures obtained with the nominal photographic calibration model. The print is processed and measured with the print densitometer 48. Outputs are obtained in the RGB channels. These output print densities are compared to certain RGB aim print densities. These aim print densities may arbitrarily be selected, but are desirably chosen to be near the density that most prints of normal scenes will be made. Suitable aim print densities are 0.80, 0.80, and 0.80, for the RGB channels. Based on the differences resulting from the comparison the exposure is adjusted and another print is made until a print close to the desired aim print densities is measured. It may be desirable to calculate the change in exposure for automatically controlling the exposure during verification of nominal balance. For example the slope of the print density vs. log exposure curve for the red, green and blue components can be

- 21 -

determined or estimated. The difference between the aim RGB print densities and the actual RGB print densities is determined and then divided by the RGB paper slope to obtain RGB log exposure deltas. These deltas are then added to the original RGB log exposures to obtain the changed exposures which will provide prints more closely approaching the aim print densities.

After nominal balance is verified, the 51 calibration prints are made as indicated at 94 in FIG. 6. These are the gamut prints which are used in calculating the photographic calibration model. These prints are made using the designed offsets to the RGB printing densities of the calibration patches as shown in Table 1 above. The offsets may be obtained by applying the then current photographic calibration model to the RGB printing densities with the offsets added to determine the control input signals to the exposing device 20. If no previous data exists for the system a nominal photographic calibration model is selected as discussed above. The closer the model selected is to the resulting model, the more efficient will be the computations and less iterations will be needed. As noted above, there are three different sets of exposure deltas for each calibration patch, 17 x 3 or 51 calibration prints are made. These are called the gamut prints.

Next, the calibration print densities are measured using the print densitometer 48. This is shown at 96 in FIG. 3. From the RGB printing densities from the calibration patches, the log exposures used in making the calibration prints (gamut log exposures) and the gamut print densities, which constitutes a

- 22 -

comprehensive base of statistical information, a regression calculation is performed, as shown at 98 to obtain the photographic calibration model. The program for carrying out this regression calculation is shown in FIG. 7. Multiple regressions are used which are indicated at 100, 102 and 104 in the flow-chart. The first regression 100 is calculated using the RGB printing densities of the calibration patches (without the offsets added), the RGB log exposures and, in the case of a variable exposure time lamphouse as is the case for the shutter equipped lamphouse 20 (FIG. 2), the log of the exposure times, (indicated as log Time) and any other variables relevant to the exposing device or the processing chemistry as the independent variables, and the RGB print densities from the calibration prints as the dependent variables. The regression equation is set forth below. The matrix of coefficients and offsets are indicated in the equation.

$$P * M_p + E * M_E + T * M_T + O + \epsilon = P.D. \quad (2)$$

where:

P is the 51×3 matrix of calibration negative printing densities (17 negative printed 3 times).

M_p is the 3×3 matrix of regression coefficients that are multiplied with the calibration negative printing densities.

- 23 -

E is the 51 x 3 matrix of RGB Log Exposures for the calibration prints.

M_E is the 3 x 3 matrix of regression coefficients that are multiplied with the Log Exposures.

T is the 51 x 1 matrix of the log of the exposure time for each of calibration prints.

M_T is a 1 x 3 matrix that is multiplied with the log of the exposure times.

O is the 1 x 3 matrix of regression offsets.

ϵ is the 51 x 3 matrix of errors between the calculated values of P.D. and the measured values of P.D. The sum of the squares of all ϵ values is minimized.

P.D. is the 51 x 3 matrix of RGB calibration print densities.

- 24 -

In another computation, 106, the predicted RGB print densities are calculated using the matrix of coefficients and matrix of offsets from the first regression computation 100. In the next three parts of the program, 108, 102, 110 and 112, the RGB print densities which are measured in process 96 in FIG. 6 (the gamut print densities) are linearized. This is done so that the relationship between predicted print density and measured print density is linear. The 3 channels may be linearized separately and the process performed at 108, 102, 110, 112 are performed for each color. First the predicted print density which was calculated at 106 is raised to an arbitrary power. This power can be chosen to be reasonably close to that which is required, as described below. Then, the regression calculation 102 is carried out with the predicted print densities raised to a power as the independent variables (51 x 1 matrix) and the measured print densities for the same color (red, green or blue) as the dependent variables (another 51 x 1 matrix). The regression is iterated using a different power that will reduce the standard error of the regression in step 102 until a standard error minimum is reached as indicated in step 110. This procedure is commonly called non-linear regression. Other methods may be used to linearize the P.D. such as the use of look-up tables. The power and regression slope and offset are saved in storage either in the CPU 52 or disk storage 54 (FIG. 3). The print density for the minimum standard error is calculated in step 112 using the following equation.

$$\text{linearized P.D.} = ((\text{P.D.} - (\text{offset})/\text{slope}))^{1/\text{power}} \quad (3)$$

- 25 -

In the final regression calculation, 104, the same variables are used as in the first regression 100 except that the dependent variables are switched with certain of the independent variables, and linearized print densities replace the original print densities, as shown in the blocks 100 and 104. In using the RGB calibration patch printing densities, the linearized RGB print densities from step 112 and any other variables relevant to the exposing device such as the log of the exposure time, or process chemistry variables as the independent variables, and the RGB log exposures from step 94 in FIG. 6 as the dependent variables, the regression is calculated. A similar equation as indicated above for the first regression computation 100 is used. The regression provides a model that will predict RGB log exposures from negative densities and desired print densities.

The regression offsets are then adjusted in the final step of the regressions in the calibration computation as indicated at 114. The aim print densities (eg. 0.80, 0.80, 0.80) for the RGB channels are linearized with the RGB slopes (the matrix coefficients), offsets and powers which were saved when the standard error was a minimum. The aim print densities are multiplied by the 3 x 3 part of the matrix obtained during the last regression 104 which contains the coefficients for the linearized print densities. This results in RGB offsets that are added to the RGB regression offsets from the regression computation 104 and adjust these offsets.

Using the photographic calibration model in the photographic compensation logic 44 (FIG. 1), the RGB

- 26 -

densities of the production negatives are multiplied by the 3 x 3 part of the matrix from the regression step 104 that contains the coefficients for the calibration patch density as independent variables. Then the adjusted RGB offsets are added to provide the log exposures.

In computing the exposure device calibration model to be used in the exposing device logic 50, an absolute photographic calibration is not necessary. The only requirement is that if a change is made to the exposing device, such as replacing a burned out lamp, the calibration must determine a new model that will achieve the same results as the previous model. This can be achieved by calibrating the shutter to provide a constant known exposure time or a variable calibrated exposure time. The intensity or variable intensity is also calibrated. This is done by using a photometer system with 3 channels (RGB) with spectral sensitivities similar to the spectral sensitivity of the paper being used in the printing system. The intensity of each of the lamps can be varied with the attenuator discs 22 (FIG. 2) and the intensities measured with the RGB photometer system. A table of intensity vs. attenuation disc 22 position is generated for each color.

In using the exposing device calibration model (FIG. 8), the RGB log exposures are sent to the exposing device logic. In the first computation 120, the logarithm of the exposure time is subtracted from each log exposure to obtain log intensities. Using the calibration tables generated to look up which position of the attenuator discs 22 provide those log intensities for each color. Iterations of comparisons of log

- 27 -

intensities with corresponding disc positions (122) and modification of exposure times are carried out. If one or more of the RGB log intensities is not available in the calibration tables, the exposure time must be adjusted accordingly in such a way that the new log intensities resulting will be available at the attenuator disc positions given in the table. The discs and shutter are set and the negative is exposed.

From the foregoing description it will be apparent that there has been provided an improved system for calibration and control of the exposing device in a photographic color printer. While an exemplary embodiment of the system has been described, variations and modifications thereof, within the scope of the invention, will undoubtedly suggest themselves to those skilled in the art. Accordingly the foregoing description should be taken as illustrative and not in a limiting sense.

- 28 -

Claims

1. In a photographic printing system for exposing a printing medium through film negatives with light having color components of different intensity and/or different exposure times and having a film densitometer for detecting the density of the negatives and an exposure device for providing said light having said color components with different intensities and/or exposure times, an improved system which calibrates the printing system to expose said printing medium through said negatives to provide upon processing of said medium in a processing system prints of desired density irrespective of the variations in density measurement and spectral response of said densitometer, printing medium, processing system and exposure device, which calibration system comprises a set containing a plurality of negative film patches including a first plurality of patches which vary in neutral density and second pluralities of patches of different color, each of said second pluralities including a plurality of patches of different density such that said set includes substantially the entire range of negative densities encountered in an average population of color negatives, means utilizing said patches for deriving a calibration model of said densitometer which emulates the response of said printing medium, means utilizing said patches and a plurality of gamut prints made with different combinations of color component intensities of each of said patches for deriving a photographic calibration model which relates the density of said negatives to the density of the prints made by exposing and processing said printing medium, and exposure control means

- 29 -

utilizing said densitometer calibration model and said photographic calibration model for controlling the color component intensities and exposure times in said exposure device.

2. The improved system according to Claim 1 further comprising means responsive to the outputs of said densitometer for providing transfer densities for each RGB color component in a film negative, means for processing said transfer densities with said photographic calibration model to provide RGB log exposure signals to said exposure control means.

3. The improved system according to Claim 1 wherein said photographic calibration model deriving means includes means utilizing said densitometer and said densitometer calibration model to verify the balance in the densities of the color components of said patches.

4. The improved system according to Claim 1 wherein said densitometer calibration model deriving means comprises means using the patches to obtain digital data representing aim printing densities for each RGB color component thereof, means for deriving digital data for each RGB color component of the patches with the densitometer, and means for carrying out a regression computation using said aim and densitometer digital data to provide said densitometer calibration model.

5. The improved system according to Claim 4 wherein said regression computation means comprises means for computing the equation

$$A * M + O + \epsilon = P$$

-30-

where A is a matrix of said densitometer digital data, M is a regression matrix, O is a matrix of regression offsets, P is a matrix of the aim densities, and Σ is a matrix of errors between the calculated values of P, the sum of the squares of all Σ values being minimized, and said densitometer model is utilized by multiplying digital data for each pixel in a matrix of pixels representing the output of said densitometer by said matrix of coefficients and adding said matrix of offsets.

6. The improved system according to Claim 1 wherein said means for deriving said photographic calibration model includes means for carrying out a regression computation using digital data representing the densities of the RGB color components of said prints, the densities of the RGB color components of the set of negative film patches, and the RGB log exposures used to expose the prints, to derive matrices of coefficients and offsets.

7. The improved system according to Claim 6 wherein said regression computation means includes means for computing the equation

$$P * M_p + E + M_E + O + \Sigma = P.D.$$

where P is a matrix of the negative printing densities, M_p is a matrix of regression coefficients which is multiplied with the densities of the negative patches, E is a matrix of the log exposures, M_E is the matrix of regression coefficients that are multiplied with the log exposures, O is a matrix of regression offsets, P.D. is the matrix of print densities obtained from the printer, and Σ is a matrix of errors between the calculated values of P.D. and the measured (from the prints) values of P.D., the sum of the squares of all Σ values being minimized.

- 31 -

8. The improved system according to Claim 7 wherein said photographic model deriving means further comprises means for carrying out a computation to linearize P.D.

9. The improved system according to Claim 8 wherein said photographic model deriving means further comprises means for carrying out another computation using the coefficients (slope) and offsets to linearize P.D. by reiterating the regression using different power until an error minimum is reached by carrying out the equation:

$$\text{linearized P.D.} = ((\text{P.D.} - (\text{offset/slope}))^{1/\text{power}})$$

10. The improved system according to Claim 8 wherein means are provided for carrying out another regression computation by said photographic calibration model deriving means using interchange of certain dependant and independant variables in the equation set forth in Claim 7.

11. The improved system according to Claim 9 wherein another regression computation is carried out by said photographic calibration model deriving means using said linearized P.D., to replace the original P.D. and the other variables contained in the equation set forth in Claim 7.

12. The improved system according to Claim 1 wherein said first and second pluralities of patches each include negative patches having different densities (exposed at different f-stops).

13. The improved system according to Claim 12 wherein said second plurality of patches comprises four different colors.

- 32 -

14. The improved system according to Claim 12 wherein said combinations of color component intensities are obtained by means for exposing said each of said patches with different exposure variations.

15. The improved system according to Claim 13 wherein said second plurality of patches comprises two sets of orthogonal colors.

1/8

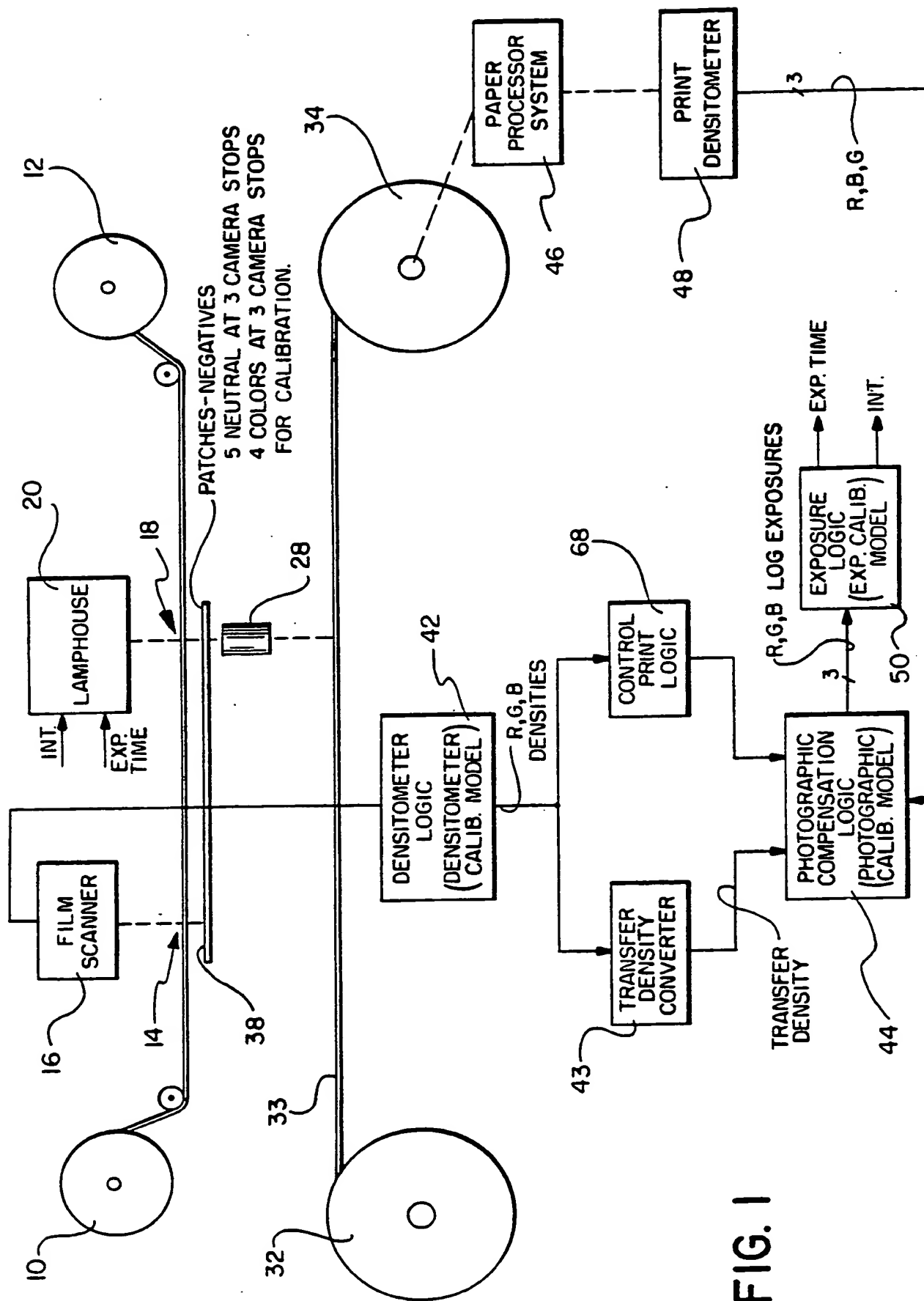
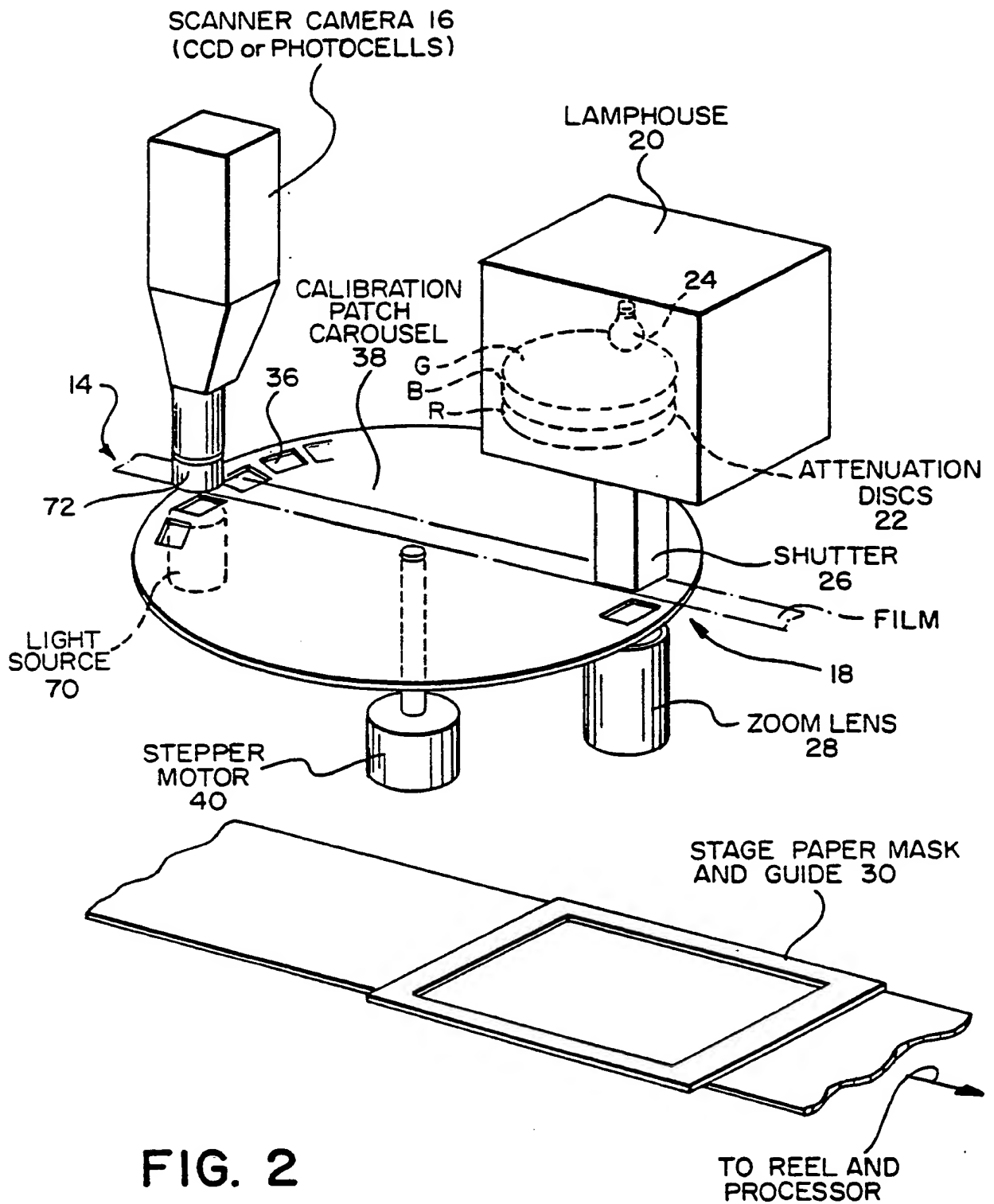


FIG. 1

2/8



3/8

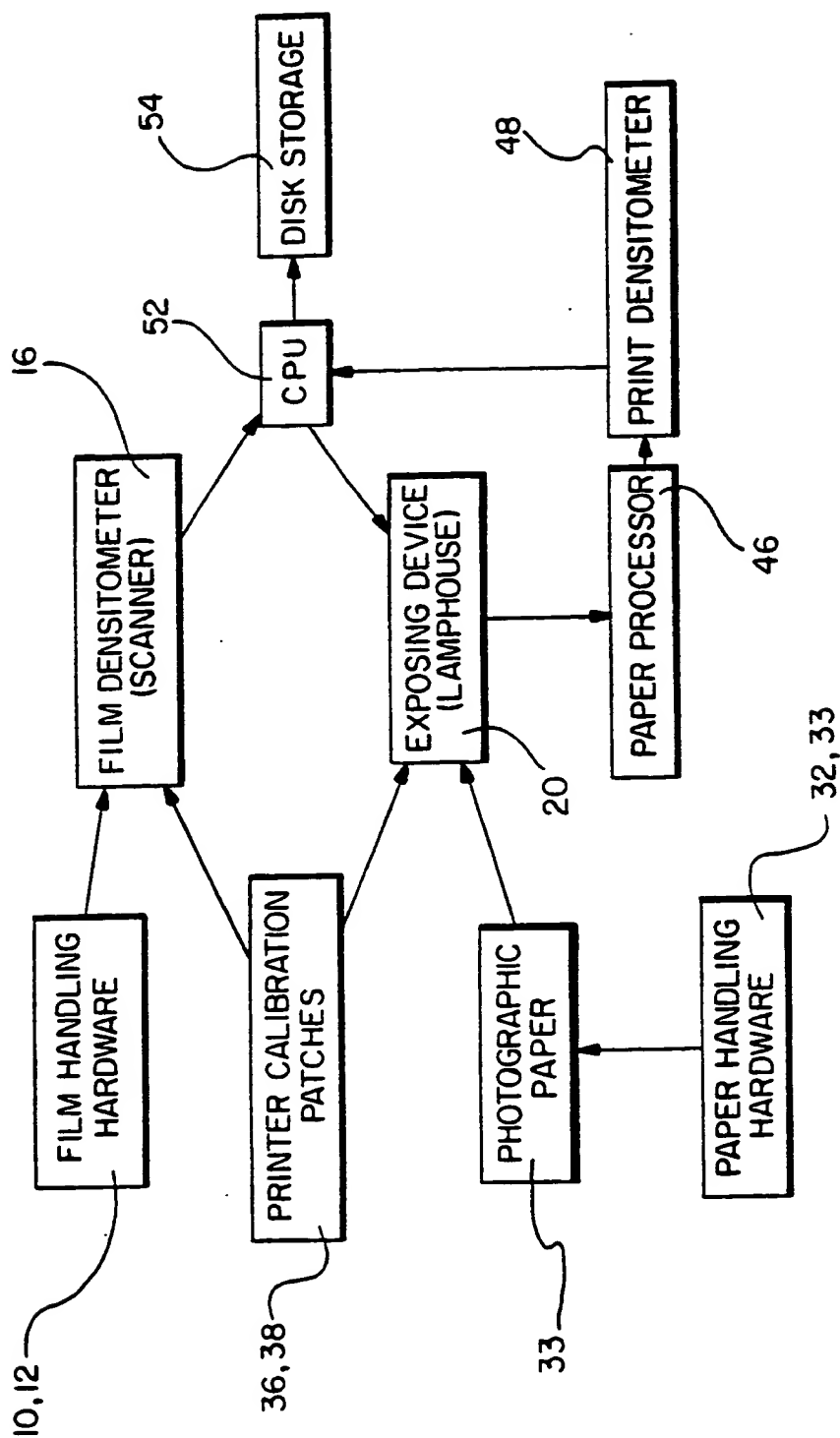


FIG. 3

4/8

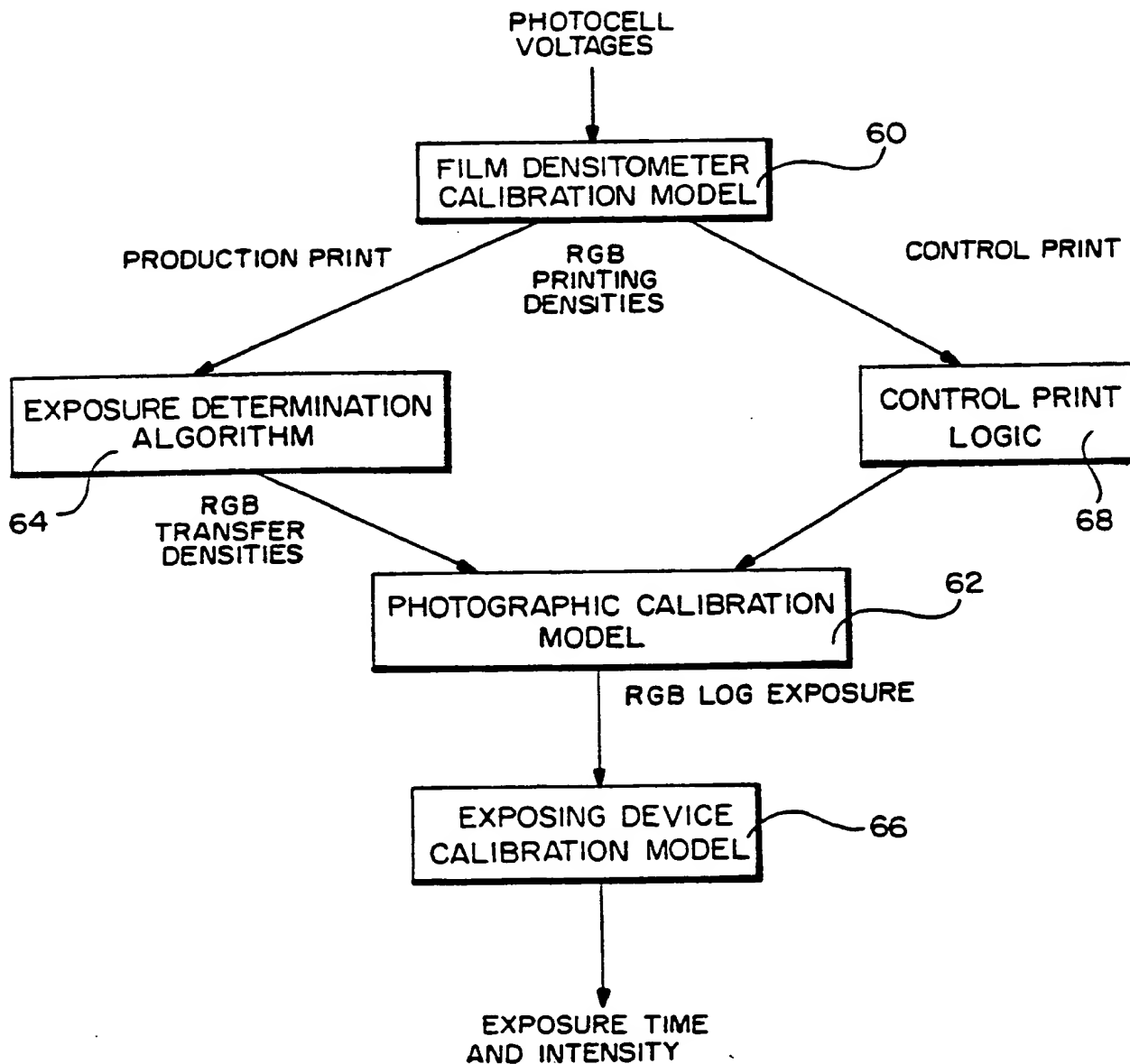
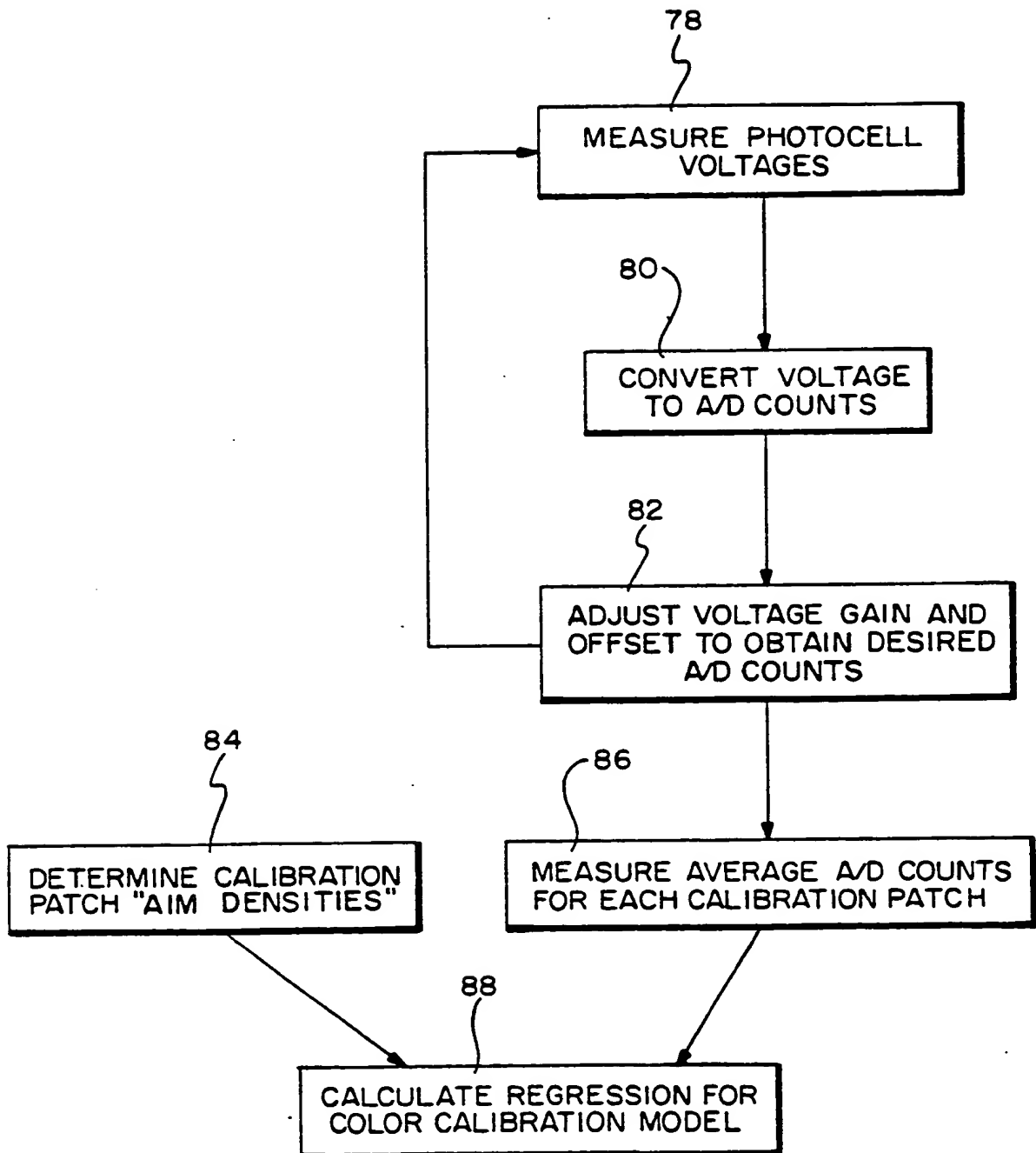


FIG. 4

5/8

FIG. 5



6/8

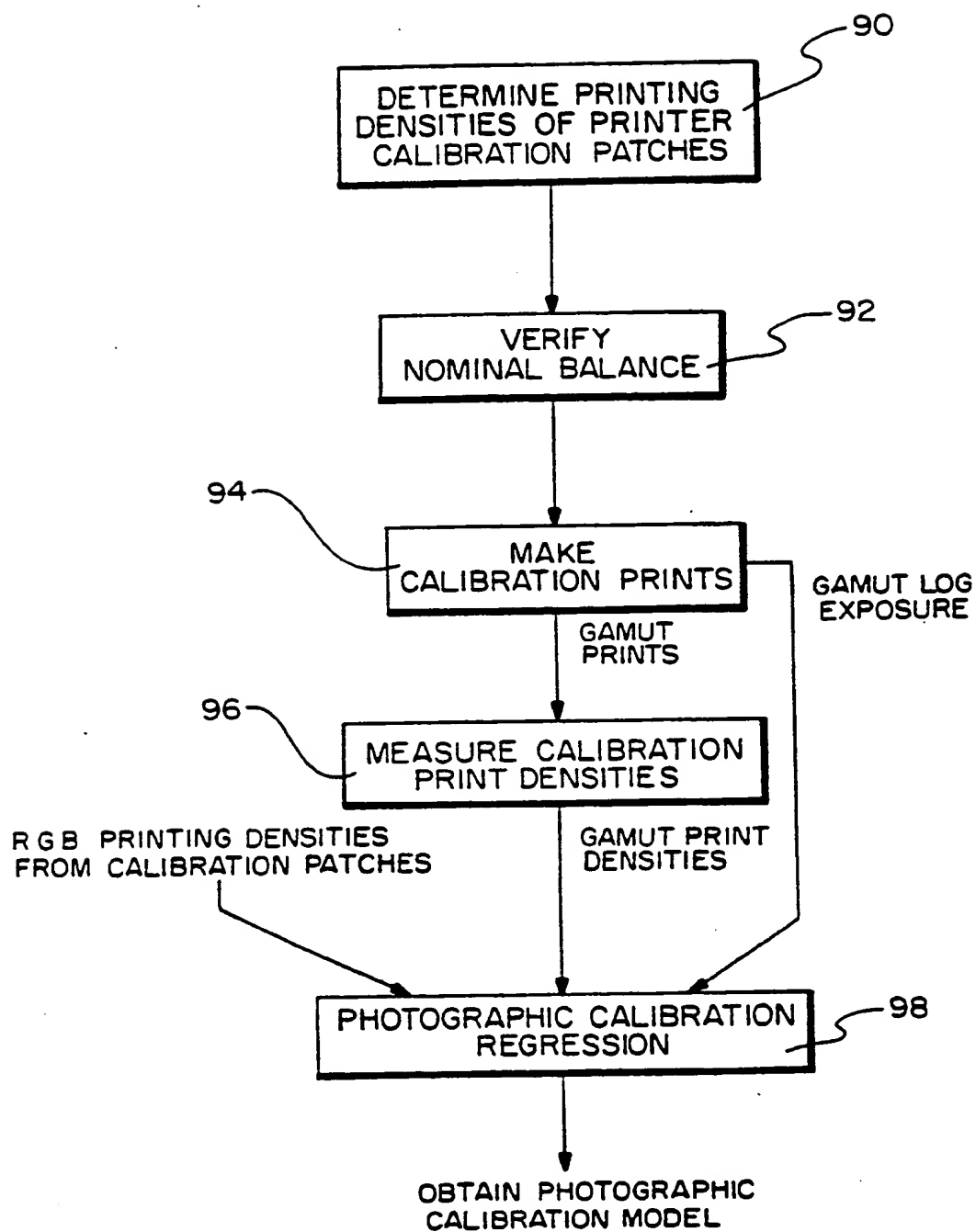


FIG. 6

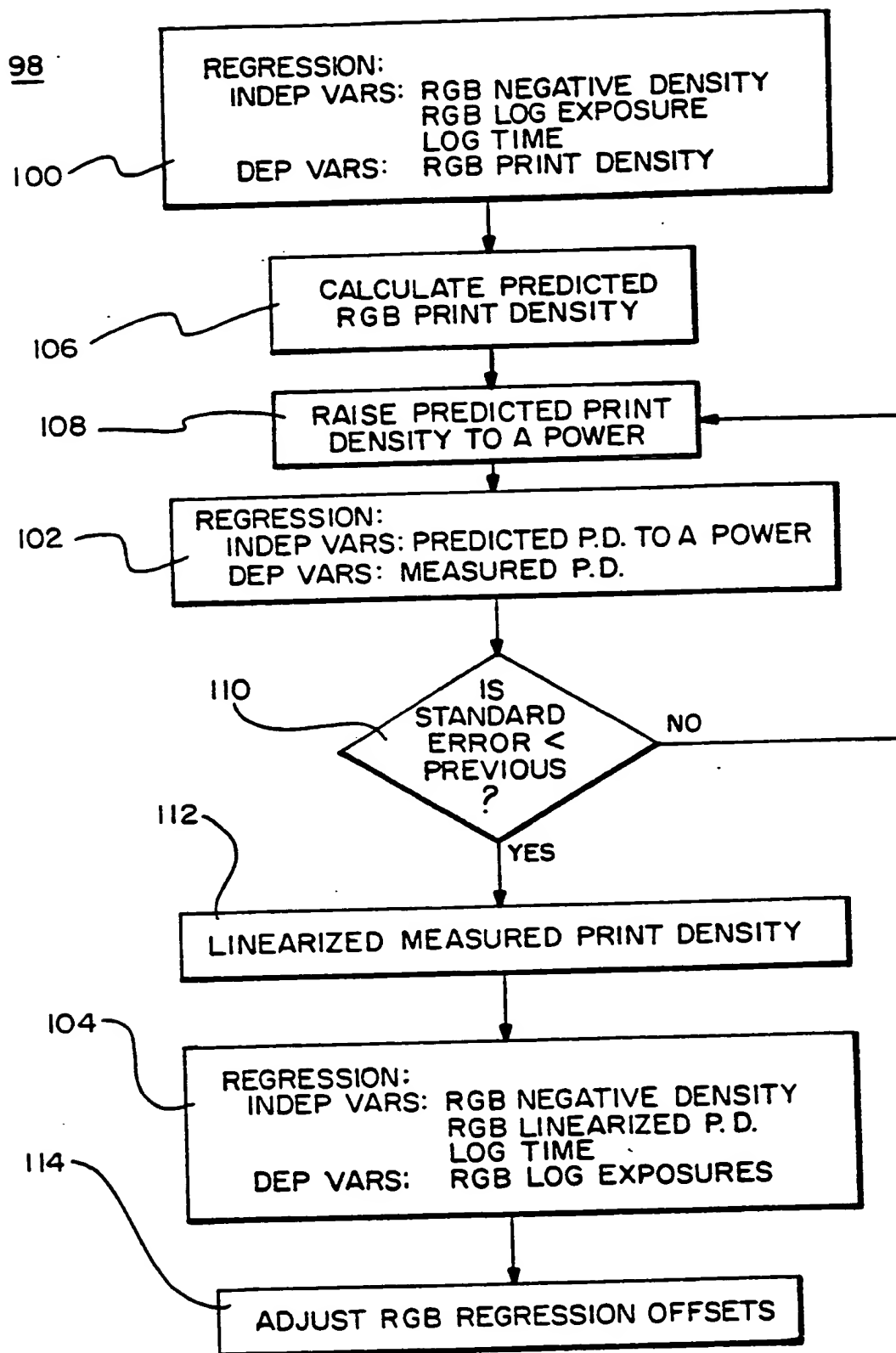


FIG. 7

8/8

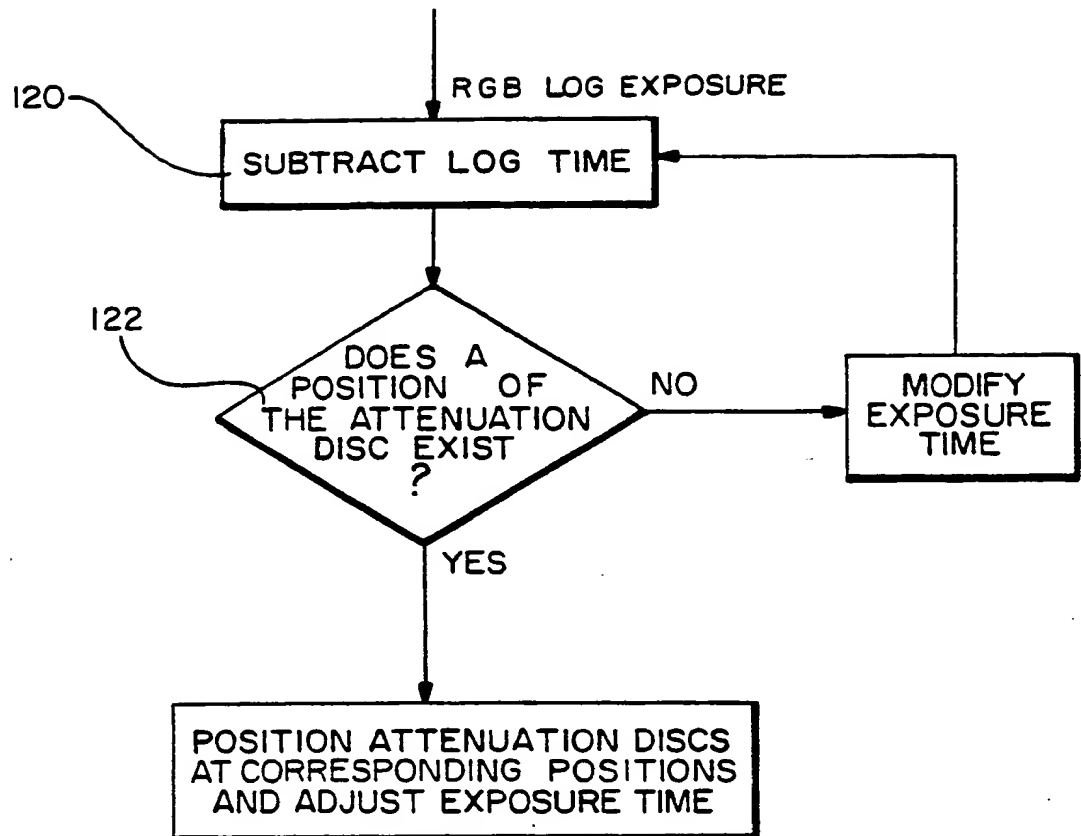


FIG. 8

INTERNATIONAL SEARCH REPORT

International Application No PCT/US 87/02531

I. CLASSIFICATION OF SUBJECT MATTER (If several classification symbols apply, indicate all) ⁶ According to International Patent Classification (IPC) or to both National Classification and IPC IPC ⁴ : G 03 B 27/73																										
II. FIELDS SEARCHED <div style="text-align: center; margin-top: 5px;">Minimum Documentation Searched ⁷</div> <table style="width: 100%; border-collapse: collapse;"> <tr> <th style="width: 30%; border-bottom: 1px solid black;">Classification System</th> <th style="border-bottom: 1px solid black;">Classification Symbols</th> </tr> <tr> <td style="padding: 5px;">IPC⁴</td> <td style="padding: 5px;">G 03 B 27/73; G 03 B 27/80</td> </tr> </table> <div style="margin-top: 5px; font-size: small;"> Documentation Searched other than Minimum Documentation to the extent that such Documents are included in the Fields Searched ⁸ </div>			Classification System	Classification Symbols	IPC ⁴	G 03 B 27/73; G 03 B 27/80																				
Classification System	Classification Symbols																									
IPC ⁴	G 03 B 27/73; G 03 B 27/80																									
III. DOCUMENTS CONSIDERED TO BE RELEVANT⁹ <table style="width: 100%; border-collapse: collapse;"> <tr> <th style="width: 10%; border-bottom: 1px solid black;">Category ⁹</th> <th style="border-bottom: 1px solid black;">Citation of Document, ¹¹ with indication, where appropriate, of the relevant passages ¹²</th> <th style="width: 10%; border-bottom: 1px solid black;">Relevant to Claim No. ¹³</th> </tr> <tr> <td style="text-align: center; vertical-align: top; padding: 5px;">A</td> <td style="padding: 5px;">EP, A, 0119941 (HOPE INDUSTRIES) 26 September 1984, see pages 14-28; figures 1-3 cited in the application --</td> <td style="text-align: center; vertical-align: top; padding: 5px;">1</td> </tr> <tr> <td style="text-align: center; vertical-align: top; padding: 5px;">A</td> <td style="padding: 5px;">EP, A, 0159253 (M. BERNHEIM) 23 October 1985, see pages 1-13; figure 1 --</td> <td style="text-align: center; vertical-align: top; padding: 5px;">1</td> </tr> <tr> <td style="text-align: center; vertical-align: top; padding: 5px;">A</td> <td style="padding: 5px;">US, A, 4174173 (J. PONE) 13 November 1979, see columns 2-5; figures 1,2 --</td> <td style="text-align: center; vertical-align: top; padding: 5px;">1</td> </tr> <tr> <td style="text-align: center; vertical-align: top; padding: 5px;">A</td> <td style="padding: 5px;">Research Disclosure, vol. 177, no. 127, November 1974 (Havant, GB), "Tone correction for color analysers", abstract no. 12727, see pages 24-26 --</td> <td style="text-align: center; vertical-align: top; padding: 5px;">1</td> </tr> <tr> <td style="text-align: center; vertical-align: top; padding: 5px;">A</td> <td style="padding: 5px;">DE, A, 2911566 (AGFA-GEVAERT AG) 2 October 1980, see pages 9-18; figures 1-4 --</td> <td style="text-align: center; vertical-align: top; padding: 5px;">1</td> </tr> <tr> <td style="text-align: center; vertical-align: top; padding: 5px;">A</td> <td style="padding: 5px;">WO, A, 82/01083 (PAKO CORP.) 1 April 1982, see pages 4-8; figure 1 --</td> <td style="text-align: center; vertical-align: top; padding: 5px;">1</td> </tr> <tr> <td style="text-align: center; vertical-align: top; padding: 5px;">A</td> <td style="padding: 5px;">US, A, 3612683 (T.E. RILEY) 12 October 1971, see claims 2-5; figure 1 -----</td> <td style="text-align: center; vertical-align: top; padding: 5px;">1</td> </tr> </table> <div style="margin-top: 5px; font-size: x-small;"> <div style="display: flex; justify-content: space-between;"> <div style="width: 45%;"> <p>⁹ Special categories of cited documents: ¹⁰</p> <p>"A" document defining the general state of the art which is not considered to be of particular relevance</p> <p>"E" earlier document but published on or after the international filing date</p> <p>"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</p> <p>"O" document referring to an oral disclosure, use, exhibition or other means</p> <p>"P" document published prior to the international filing date but later than the priority date claimed</p> </div> <div style="width: 45%;"> <p>"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</p> <p>"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step</p> <p>"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.</p> <p>"A" document member of the same patent family</p> </div> </div> </div>			Category ⁹	Citation of Document, ¹¹ with indication, where appropriate, of the relevant passages ¹²	Relevant to Claim No. ¹³	A	EP, A, 0119941 (HOPE INDUSTRIES) 26 September 1984, see pages 14-28; figures 1-3 cited in the application --	1	A	EP, A, 0159253 (M. BERNHEIM) 23 October 1985, see pages 1-13; figure 1 --	1	A	US, A, 4174173 (J. PONE) 13 November 1979, see columns 2-5; figures 1,2 --	1	A	Research Disclosure, vol. 177, no. 127, November 1974 (Havant, GB), "Tone correction for color analysers", abstract no. 12727, see pages 24-26 --	1	A	DE, A, 2911566 (AGFA-GEVAERT AG) 2 October 1980, see pages 9-18; figures 1-4 --	1	A	WO, A, 82/01083 (PAKO CORP.) 1 April 1982, see pages 4-8; figure 1 --	1	A	US, A, 3612683 (T.E. RILEY) 12 October 1971, see claims 2-5; figure 1 -----	1
Category ⁹	Citation of Document, ¹¹ with indication, where appropriate, of the relevant passages ¹²	Relevant to Claim No. ¹³																								
A	EP, A, 0119941 (HOPE INDUSTRIES) 26 September 1984, see pages 14-28; figures 1-3 cited in the application --	1																								
A	EP, A, 0159253 (M. BERNHEIM) 23 October 1985, see pages 1-13; figure 1 --	1																								
A	US, A, 4174173 (J. PONE) 13 November 1979, see columns 2-5; figures 1,2 --	1																								
A	Research Disclosure, vol. 177, no. 127, November 1974 (Havant, GB), "Tone correction for color analysers", abstract no. 12727, see pages 24-26 --	1																								
A	DE, A, 2911566 (AGFA-GEVAERT AG) 2 October 1980, see pages 9-18; figures 1-4 --	1																								
A	WO, A, 82/01083 (PAKO CORP.) 1 April 1982, see pages 4-8; figure 1 --	1																								
A	US, A, 3612683 (T.E. RILEY) 12 October 1971, see claims 2-5; figure 1 -----	1																								
IV. CERTIFICATION <table style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%; border-bottom: 1px solid black; padding: 5px;"> Date of the Actual Completion of the International Search 12th July 1988 </td> <td style="width: 50%; border-bottom: 1px solid black; padding: 5px;"> Date of Mailing of this International Search Report 29. 07. 88 </td> </tr> <tr> <td style="border-bottom: 1px solid black; padding: 5px;"> International Searching Authority EUROPEAN PATENT OFFICE </td> <td style="border-bottom: 1px solid black; padding: 5px;"> Signature of Authorized Officer M. VAN MOL </td> </tr> </table>			Date of the Actual Completion of the International Search 12th July 1988	Date of Mailing of this International Search Report 29. 07. 88	International Searching Authority EUROPEAN PATENT OFFICE	Signature of Authorized Officer M. VAN MOL																				
Date of the Actual Completion of the International Search 12th July 1988	Date of Mailing of this International Search Report 29. 07. 88																									
International Searching Authority EUROPEAN PATENT OFFICE	Signature of Authorized Officer M. VAN MOL																									

ANNEX TO THE INTERNATIONAL SEARCH REPORT
ON INTERNATIONAL PATENT APPLICATION NO.

US 8702531
SA 20348

This annex lists the patent family members relating to the patent documents cited in the above-mentioned international search report. The members are as contained in the European Patent Office EDP file on 21/07/88. The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
EP-A- 0119941	26-09-84	JP-A- 59181776 US-A- 4526462 US-A- 4657378	16-10-84 02-07-85 14-04-87
EP-A- 0159253	23-10-85	JP-A- 60222838	07-11-85
US-A- 4174173	13-11-79	None	
DE-A- 2911566	02-10-80	EP-A, B 0020855 JP-A- 55127581 US-A- 4464045	07-01-81 02-10-80 07-08-84
WO-A- 8201083	01-04-82	None	
US-A- 3612683	12-10-71	None	

EPD FORM P0479

For more details about this annex : see Official Journal of the European Patent Office, No. 12/82